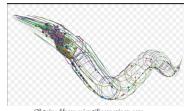
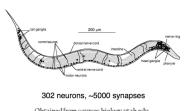


Background and Motivation

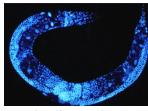
Caenorhabditis elegans (*C. elegans*) is a transparent nematode whose 302-neuron nervous system has been fully mapped. *C. elegans* started being used as a model organism about 50 years ago.



Obtained from scientificamerican.com



302 neurons, ~5000 synapses



Obtained from courses.biology.utk.edu

Obtained from macroevolution.net

We use *C. elegans* in our project in T-shaped mazes to test decision making and spatial learning. The long-term goal of this project is to discover the specifics of if and how aging affects spatial learning and consequent decisions.

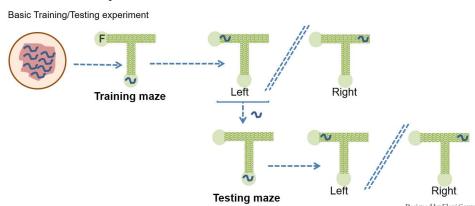


Courtesy of Eleni Gourgou



Courtesy of Eleni Gourgou

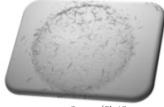
To determine if worms are capable of spatial learning, a test as depicted below was ran. Food was placed in the left end of the Training Maze, the worms who found it were placed in the Testing Maze immediately after.



The high homology between the genes of *C. elegans* and humans allow our results to reveal a substantial amount of information about aging and learning in higher organisms.

Methods

60mm diameter petri dishes to test and culture worms



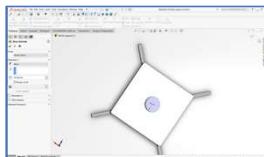
Courtesy of Eleni Gourgou

Olympus SZ61 microscope



Obtained from Nomadics.com

I use SolidWorks, a Dassault Systems Product, to design the maze molds and we print them in a Form Labs 1+ desktop 3D printer



Obtained from 3DPrint.com

References

Gourgou E., Adiga K., Hsu AL. 'C. elegans learning and decision making in T-shaped mazes', Submitted, 2018

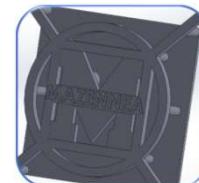
Corsi A.K., Wightman B., and Chalfie M. (18 June 2015). A transparent window into biology: A primer on *Caenorhabditis elegans*. In *WormBook* (Introduction: 8)

Abstract

We use a hydrogel called agar to culture and test out worms. It is transparent and easily manipulated. Currently we are using a T-shaped maze with a left-right decision, changes in elevation of the worm while in the maze are disregarded. I am tasked with improving the design to increase efficiency. I increased the number of mazes per dish from five to nine and eliminated post solidification prep time (trimming). Apart from the T-mazes, I designed several other types of mazes, including radial and sequential, along with a method for a removable food source. After printing all of my parts I inspect the molds themselves and the mazes they create under the microscope for defects.

The other part of my project is to develop a method to prepare 3-D mazes. This is something that has never been done before in relation to our model organism, *C. elegans*. There is a myriad of reasons why this type of maze is worth exploring. The seemingly most obvious explanation is that a 3-D test space more closely resembles the wild-type environment. In nature these worms are not limited to 2-D decisions. Classical molding techniques where agar is inserted into a mold, allowed to solidify and the mold parts are then removed have shown promising results.

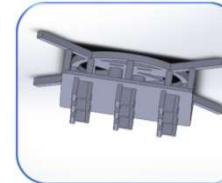
MazEnnea



Top View



Side View



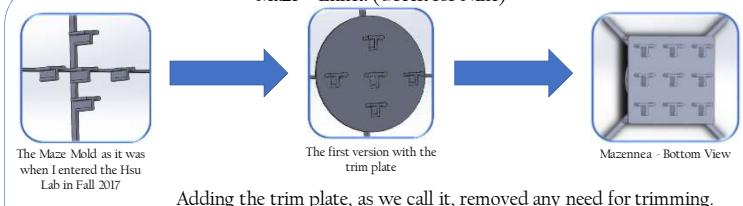
Angled Side View



Bottom View

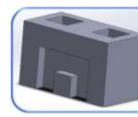
ResultsTwo-Dimensional Design

Maze + Ennea (Greek for Nine)

Three-Dimensional Design

The Archway

We print two of each of these parts, hold the mold halves together with the clips and inject liquid agar into the mold from underneath



The resulting arena can be seen here from the side

Conclusions

Adding a planar platform on the molds where the surface of the agar meets the mold removed the need for trimming, this technology has been implemented on all the maze designs.

Designing maze molds in this fashion has proven to work very well. The maze designs are as diverse as the questions they can answer. This method is easy to implement in any *C. elegans* lab.

We have formulated a new way to put food in the mazes. The worm is able to find it without being able to eat it.

Agar is rigid enough to support itself, despite being a relatively soft and wet hydrogel. This characteristic will be essential to the creation of 3D arenas.

Acknowledgements

I would like to thank the Pletcher Lab in the BSRB floor 3 for letting us use their 3D printer so extensively, Kira Barton and Lai Yu Leo Tse, Mechanical Engineering, for their assistance in our effort to develop a way to create 3D behavioral assays. Surojit Sural for always being available to answer questions and participate in discussion and for his guidance on this poster, Carol Moussian for running the lab smoothly, my fellow UROP students for creating a scientific environment and Annie Goettemoeller for being awesome.